



# Classifying Computational Problems

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Classifying Problems

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## Machines and Algorithms

In CS1, we have seen **algorithms** for various problems on two different types of **machine**:

- Finite State Machine (represented by FSM diagrams)
- “Conventional Computer” (represented by Java programs)

For each machine, certain problems seem **harder** than others, and some may be **impossible** to solve.

- searching a sorted array is “easier” than sorting the array
- checking for equal numbers of A’s and B’s in the input is impossible for a FSM

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## Problem Classes

**Classifying** problems by their **difficulty**, and noting how members of each class are related, can be useful

- stops us from trying to **solve the impossible**
- suggests that a problem might be so hard (but not impossible) that we should accept “**nearly right**” solutions

Sometimes knowing that a problem is very hard can be a positive thing - many **cryptographic** algorithms are only assumed secure because certain mathematical problems are very hard to solve.

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## Machine Models

In absolute terms, any real computer is just a Finite State Machine!

- **fixed number** of memory locations each storing a **fixed size** piece of data
- **fixed number** of transistors in the CPU etc
- so, a **finite** (but huge) number of possible **states**

For example, in the extreme, no real computer can check matching A and B counts in the input.

To make more practical progress we observe that **memory is usually effectively infinite** and model our algorithms and problem classes on this assumption.

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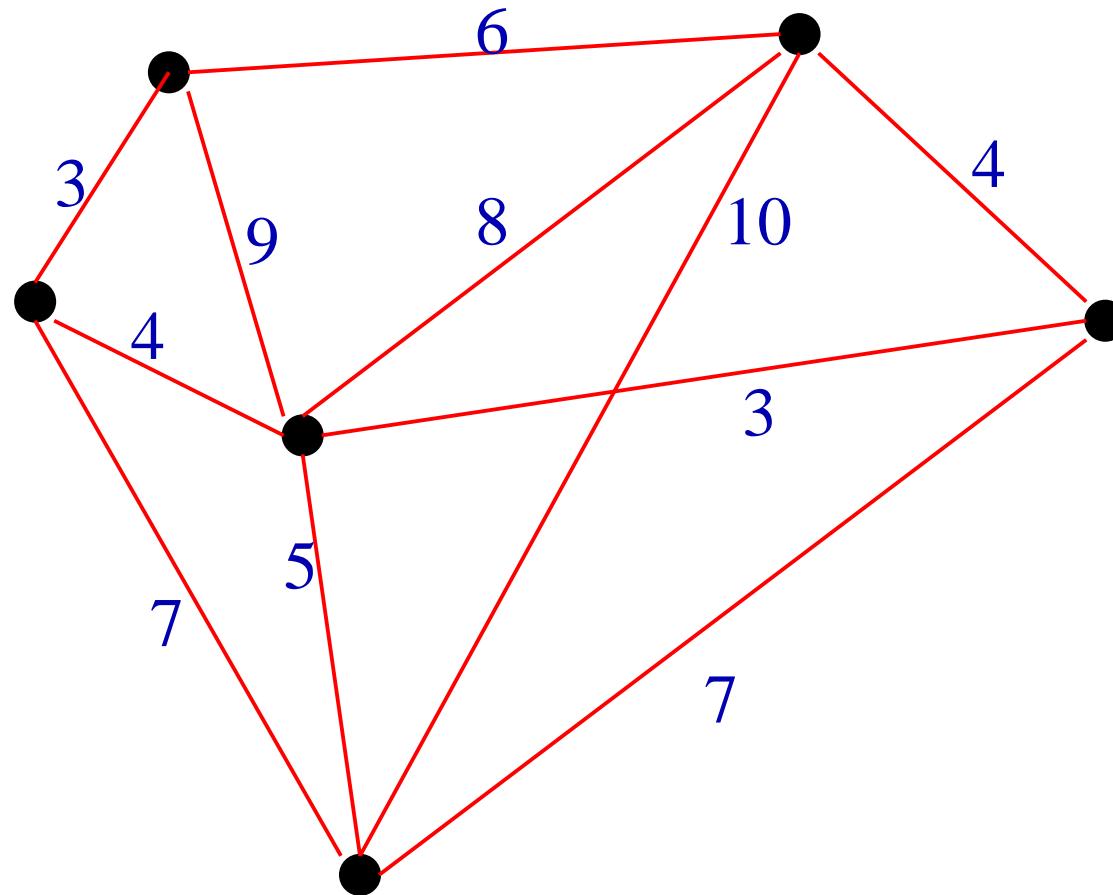
Computer Scientists group problems into several **classes**

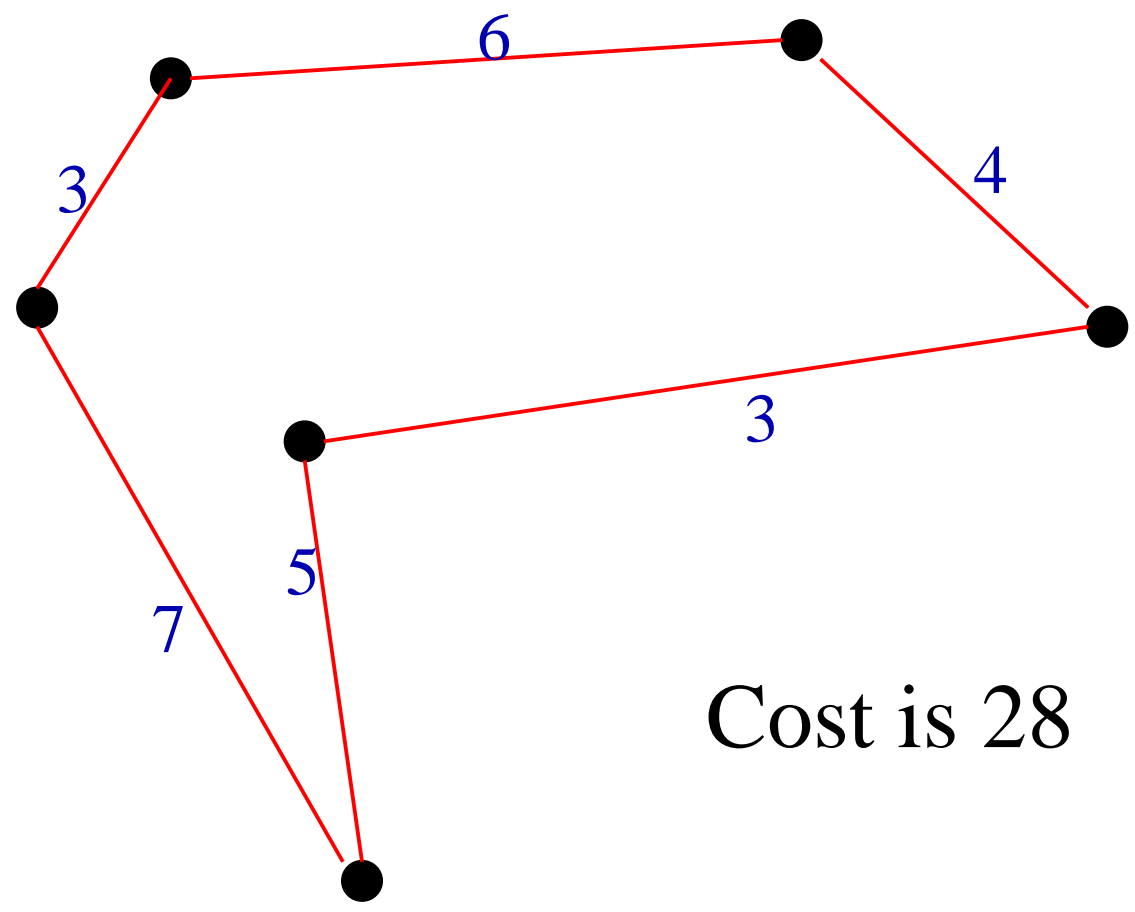
- **Easy** problems **P**, which can always be solved in time which is **polynomial** in the size of the input (e.g. searching, sorting, multiplying matrices).
- **Possibly Quite Hard** problems **NP**, which can be solved in time no worse than exponential in the input size, but perhaps faster, in the worst case. The hardest problems in the class are called **NP-Complete** and include the **Travelling Salesman Problem**.
- **Definitely Hard** problems **EXPTIME** which always take exponential time in the worst case, including the **Roadblock Problem**.
- **Impossible** problems which are **unsolvable**. The best known example is the **Halting Problem** described by Alan Turing (1936).

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## Travelling Salesman Problem

- Given a set of destinations  $D = \{d_1, \dots, d_m\}$ , and
- A set of roads  $R = \{r_1, \dots, r_n\}$  each joining two of the  $d$ 's and each having a given length,
- Find a sequence of roads making a *tour* (i.e. that adjacent roads join up and all destinations are visited at least once) such that the overall length of the tour is the shortest possible.



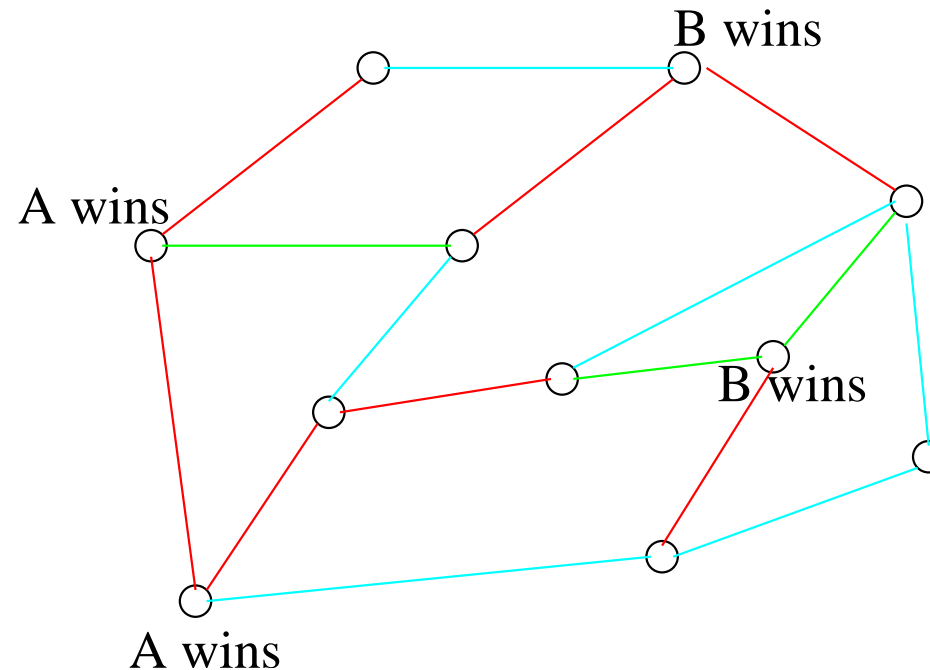


Cost is 28

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- The Travelling Salesman Problem is **NP Complete**.
  - This means that, as far as we know, there is no better way of solving it for all possible cases, than simply to **examine all the possible tours** and take the shortest.
  - Given a map with  $n$  destinations, how many possible **roads** are there?
  - Given a map with  $n$  destinations, how many possible **tours** are there?

## Roadblock Problem

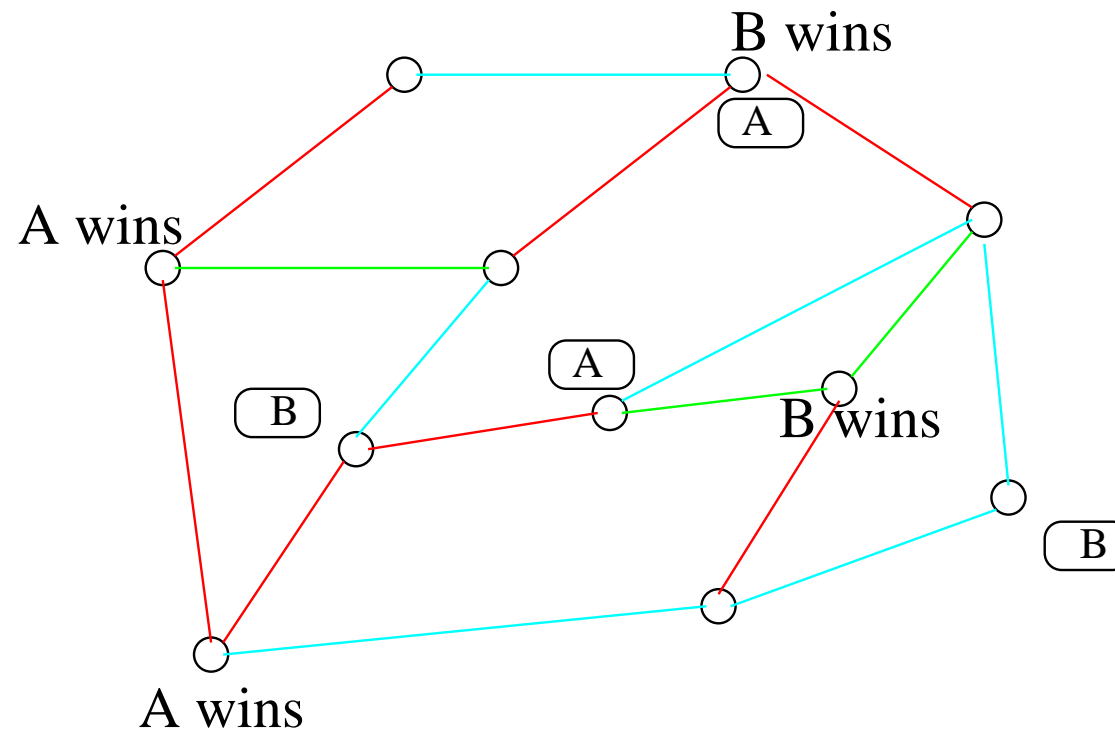
Given a road network with a collection of intersections connected by roads of three different colours. Some intersections are labelled “A wins”, some are labelled “B wins”.



Each player has a fleet of **cars**. The cars are distributed across the network and are **located at intersections**. There is **at most one car at any intersection**.

One **move** in the game is for a player to move one of their cars along a stretch of road passing a number of intersections, **keeping to the same colour of road throughout**. A car **may not** pass by or stop at an intersection that is occupied by an opponents car.

The problem is to determine if for a given starting configuration Player A (who plays first) has a **winning strategy**. That is there is a way for Player A to play that ensures they win **regardless** of the moves taken by Player B.



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## The Halting Problem

Parameterised by a program **P** and an input **I**, the Halting problem **H(P,I)** asks “Does **P** halt (finish) when run on **I**?”

This is very well defined problem. The answer is certainly either “yes” or “no” for any possible **P** and **I**.

How would you write a program to compute **H**?

It's no use actually trying to run **P** on **I**. If it stops we can return “yes”, but what if it doesn't? We can't tell how long to wait...

In fact, the problem is **impossible**. No program for **H** can exist!

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## Why is it Impossible?

We use a “proof by contradiction”: **assume** that it is possible and then show that this assumption **leads us to a contradiction**.

- Assume machine (program)  $H(P,I)$  solves the Halting Problem
- Use  $H$ , to build  $H'(X)$  which internally runs  $H(X,X)$  and
  - **Halts** if  $H$  says  $X(X)$  **doesn't halt**
  - **Doesn't halt** (infinite loop) if  $H$  says  $X(X)$  **halts**
- Think about what  $H'(H')$  does ....
- Construction of  $H'$  from  $H$  is sound, so our **only logical conclusion** is that  **$H$  can't exist in the first place!**

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## Some More Problems

Which of these problems are always solvable?

1. Given a program  $P$  and input  $I$ , **how long** does  $P$  take to process  $I$ ?
2. Given a program  $P$  and an input  $I$ , does the program need **more than 1000 bytes** of data memory?
3. Given a program  $P$ , does  $P$  **always halt**, no matter what the input?
4. Given two programs  $P_1$  and  $P_2$ , do they **always compute the same result**, given the same input?